



Physikalisch-Technische Bundesanstalt
Braunschweig and Berlin
National Metrology Institute



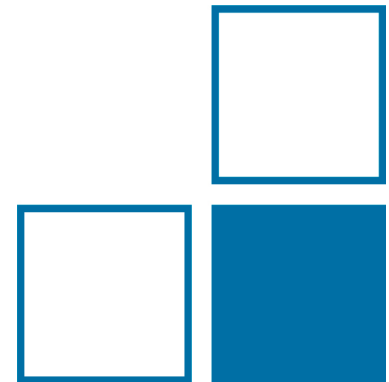
Calibration of a 30 MN Material Testing Machine According to ISO 7500-1 Using a Force-Transducer Build-Up System

*within the scope of the
EMRP SIB 63 project*

Falk Tegtmeier, Alex W. Gutsch

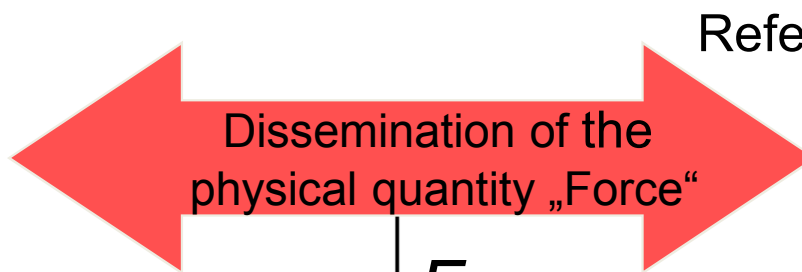
Physikalisch-Technische Bundesanstalt (PTB). Braunschweig, Germany

Materialprüfanstalt für das Bauwesen (MPA) and Technical University of Braunschweig, Germany

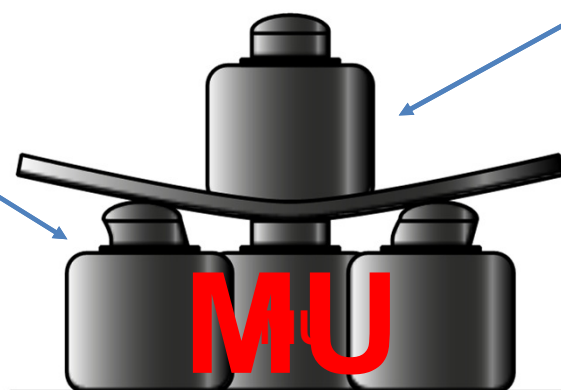




Force Standard Machine

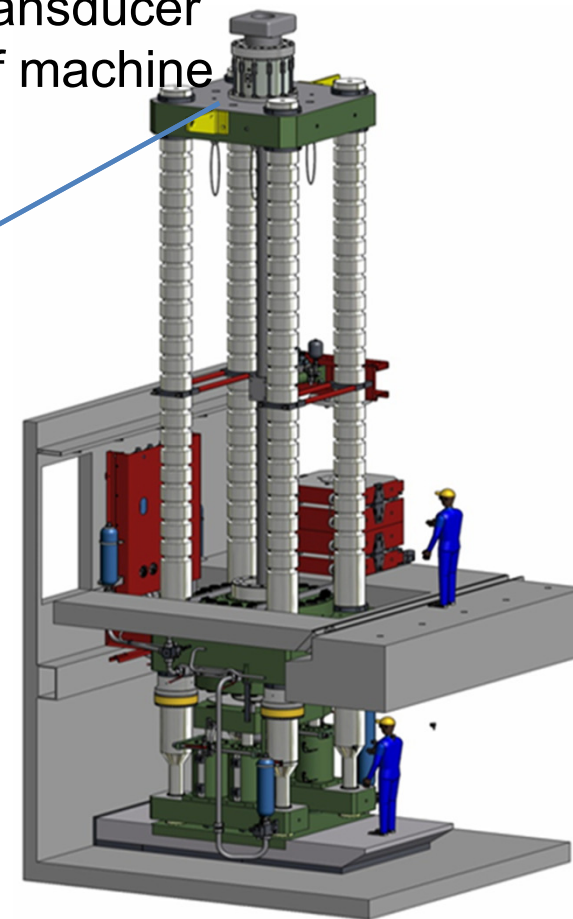


F

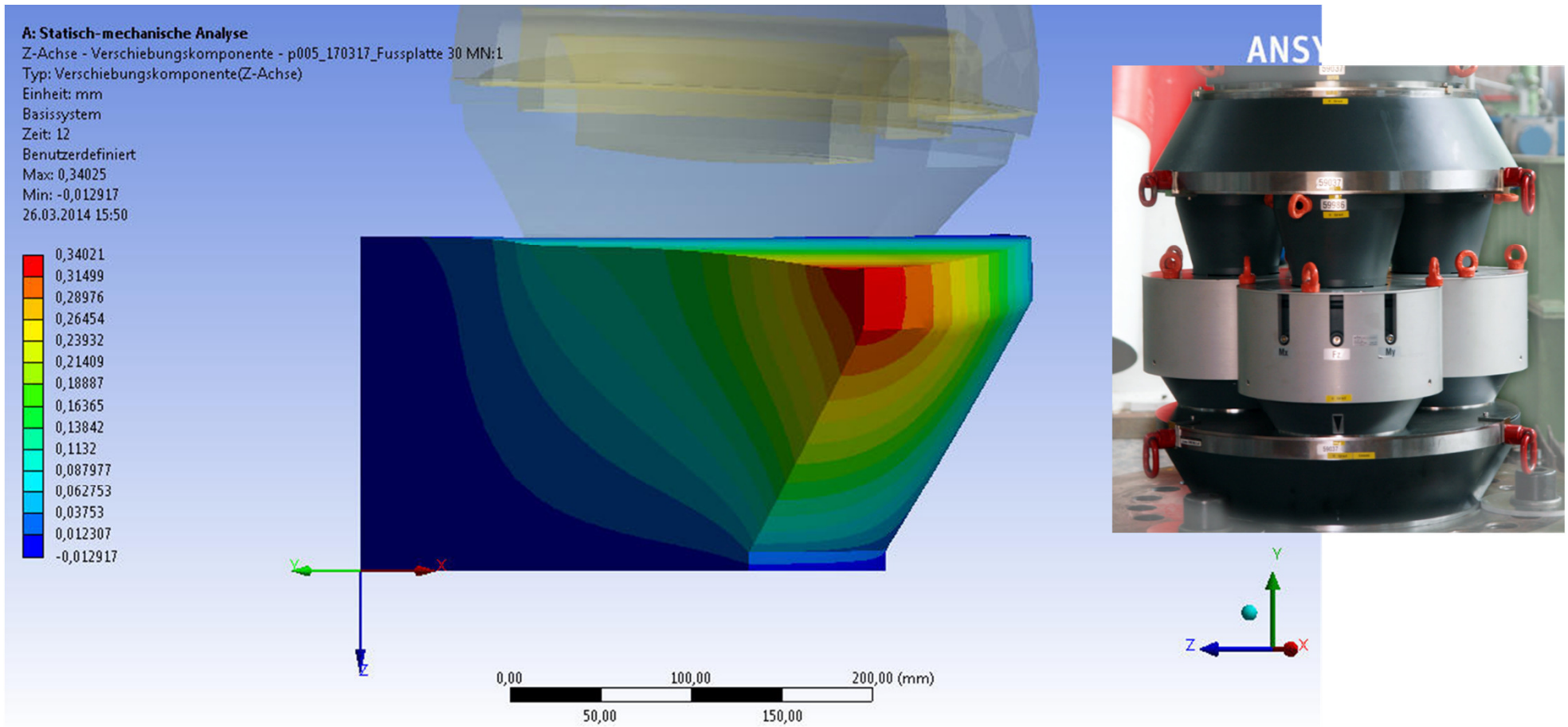


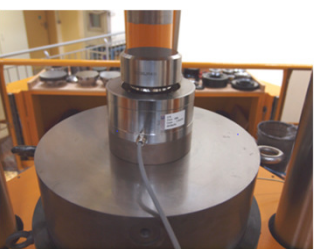
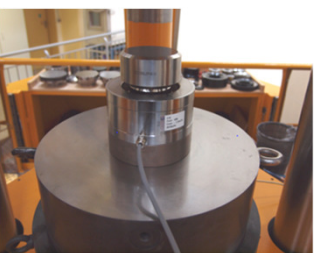
Build-Up System used as a transfer standard

Reference transducer of machine



Force Calibration Facility





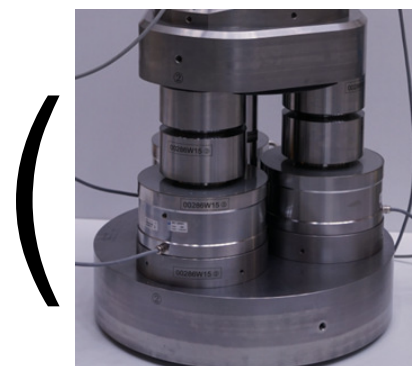
Sensitivity of single transducers

*



Applied force of the Force Standard Machine

=



Sensitivity of single transducers with the interaction of the adaptation parts

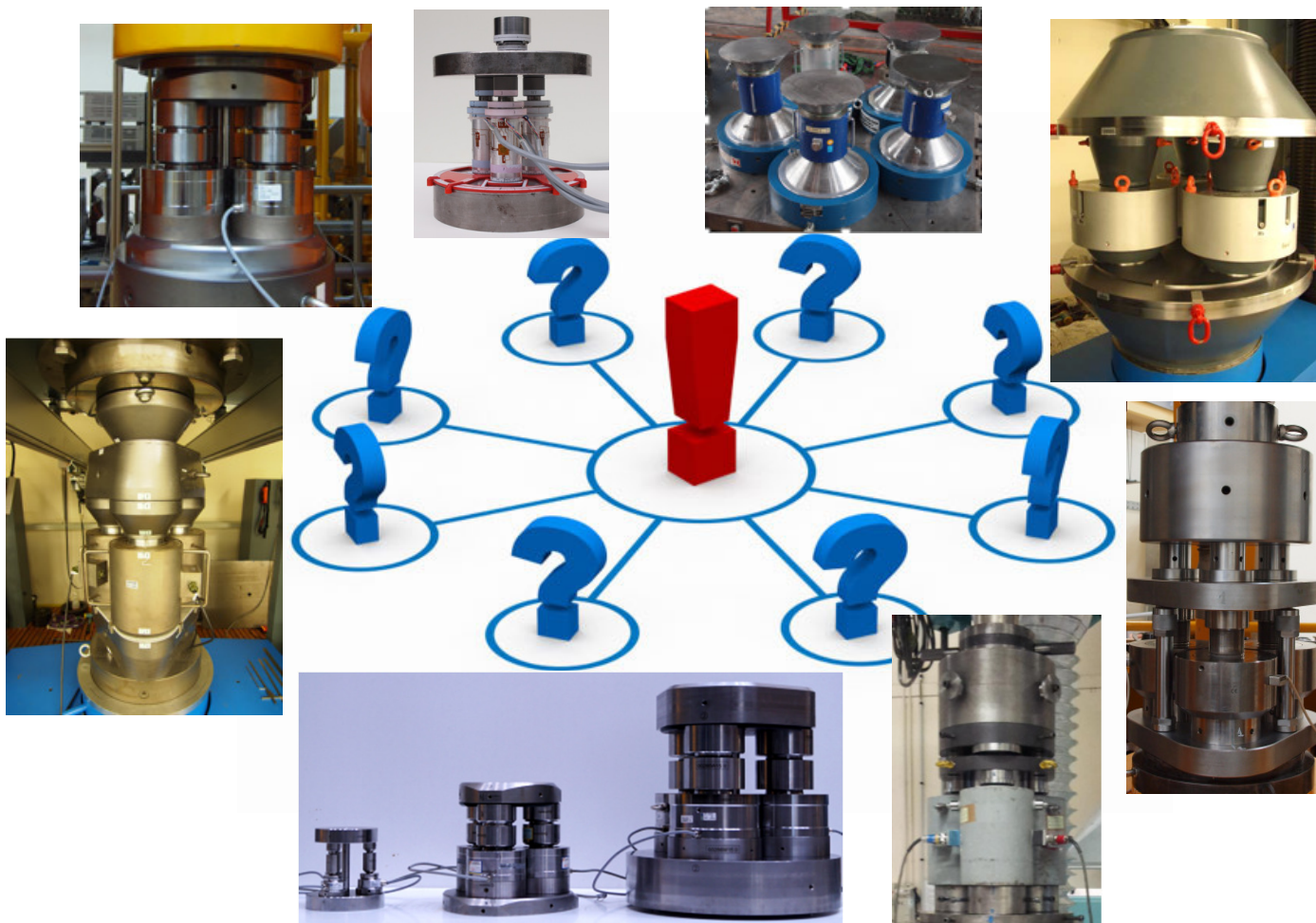
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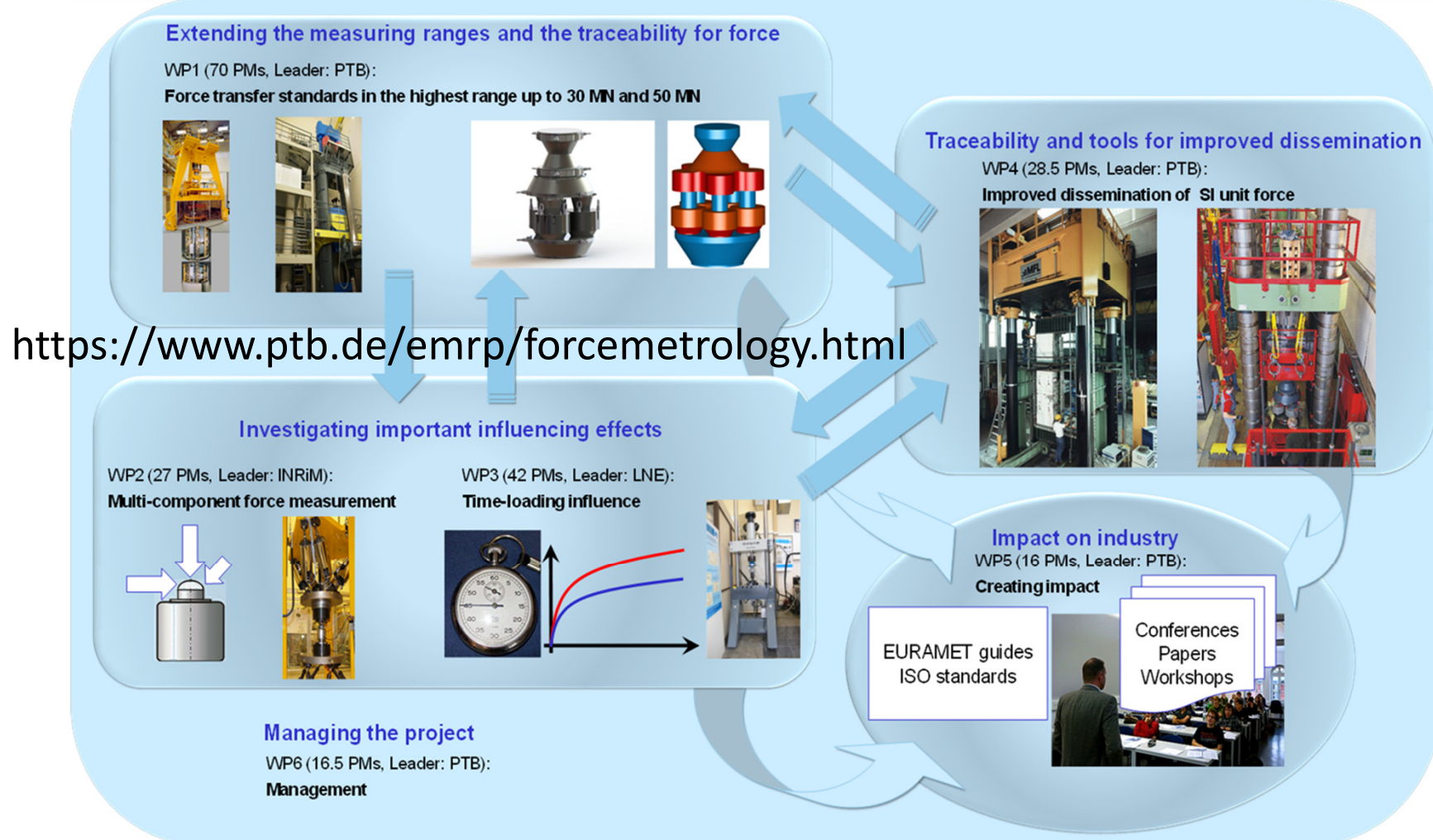


Applied force of the machine to be calibrated

$(1 + d)$

EMRP SIB 63 project: Creating of a knowledgebase for typical properties of BU Systems





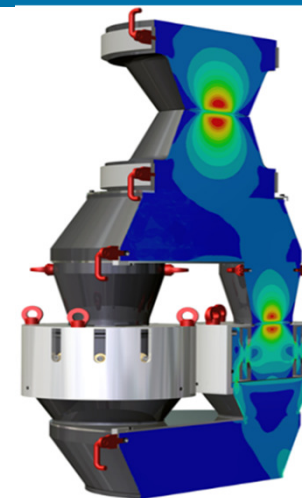
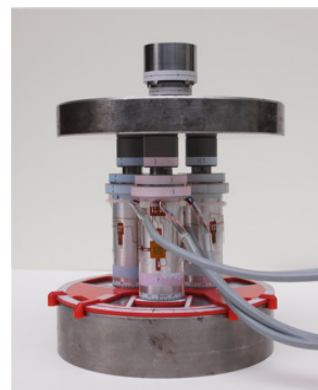
SIB63 Force

<https://www.ptb.de/emrp/forcemetrology.html>



**Final Publishable JRP Summary for SIB63 Force
Force traceability within the meganewton range**

- Investigations of different
- types of force transducers
 - bending ring transducers
 - column type transducers
 - types of adaptation parts

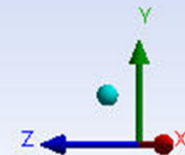
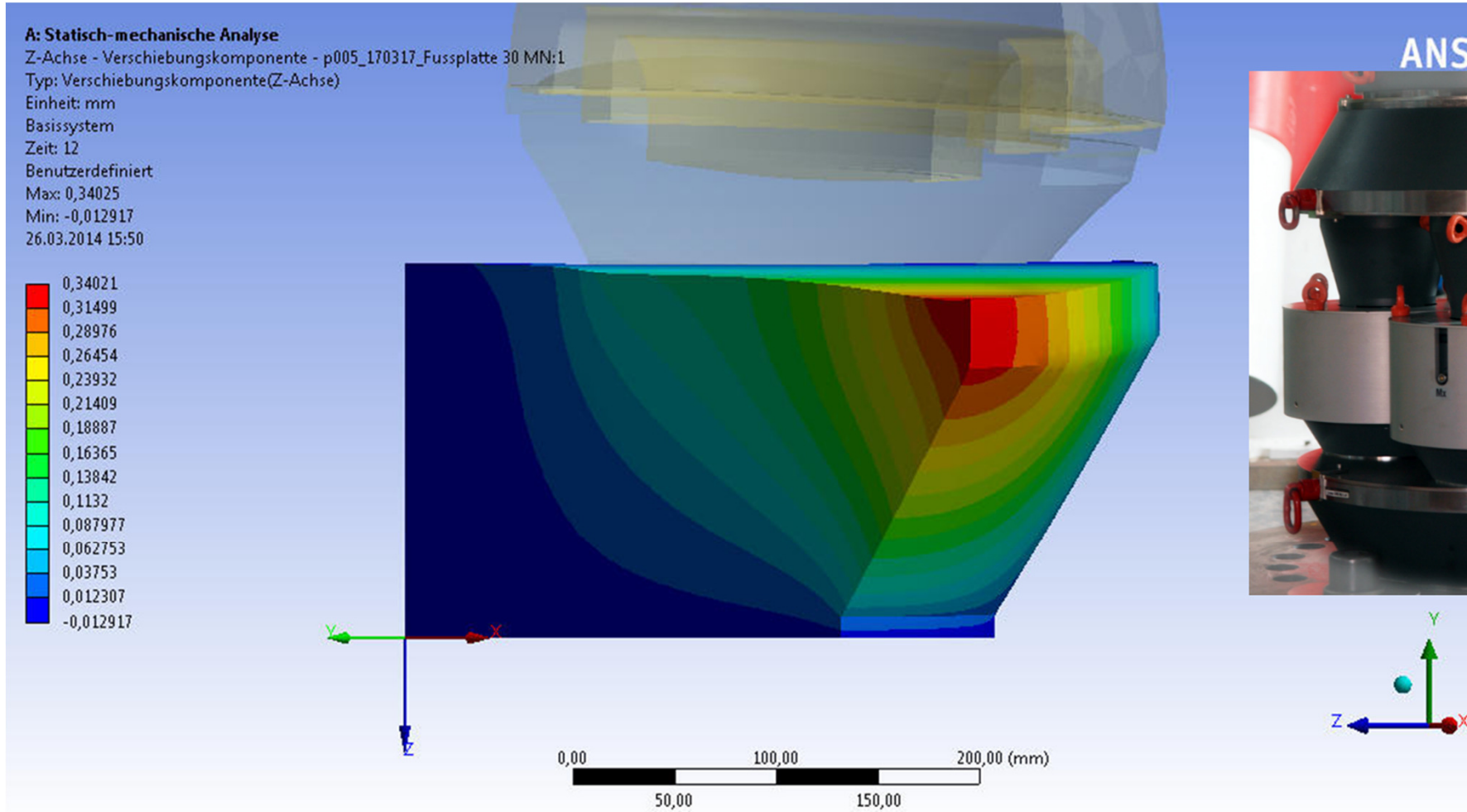


usual load cups

additional
pendulums

additional
load cup on the top

conical sphere on the top





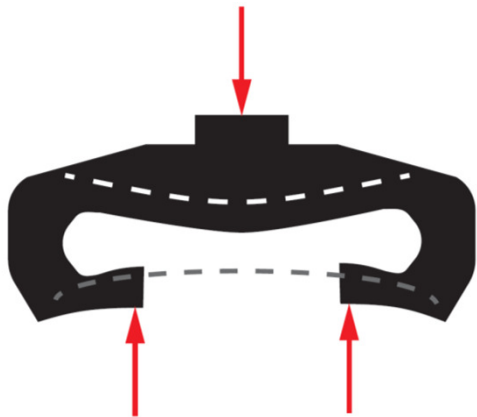
Force in kN	Deviation high stiffness $d_{L,135}$	Deviation low stiffness $d_{L,135}$
1500	-0,020%	0,131%
3000	-0,005%	0,145%
4500	0,004%	0,150%
6000	0,010%	0,151%
7500	0,011%	0,150%
9000	0,014%	0,149%
10500	0,012%	0,147%
12000	0,013%	0,145%
13500	0,013%	0,145%
15000	0,014%	0,144%
16500	0,011%	0,140%



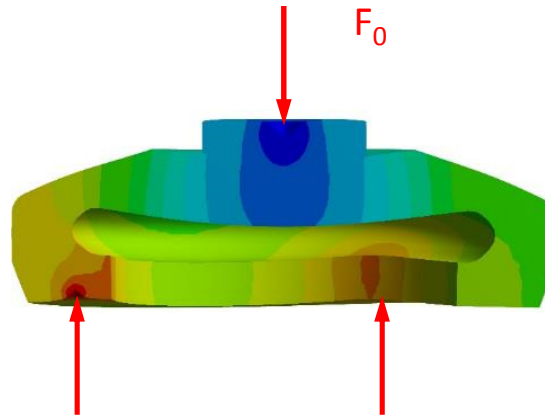


Force in kN	Deviation high stiffnes $d_{L,135}$	Deviation low stiffness $d_{L,135}$
600.00	-0.015%	-0.017%
1200.00	-0.016%	-0.020%
1800.00	-0.017%	-0.022%
2400.00	-0.018%	-0.024%
3000.00	-0.018%	-0.025%
3600.00	-0.018%	-0.026%
4200.00	-0.017%	-0.026%
4800.00	-0.017%	-0.026%
5400.00	-0.015%	-0.025%
6000.00	-0.014%	-0.024%

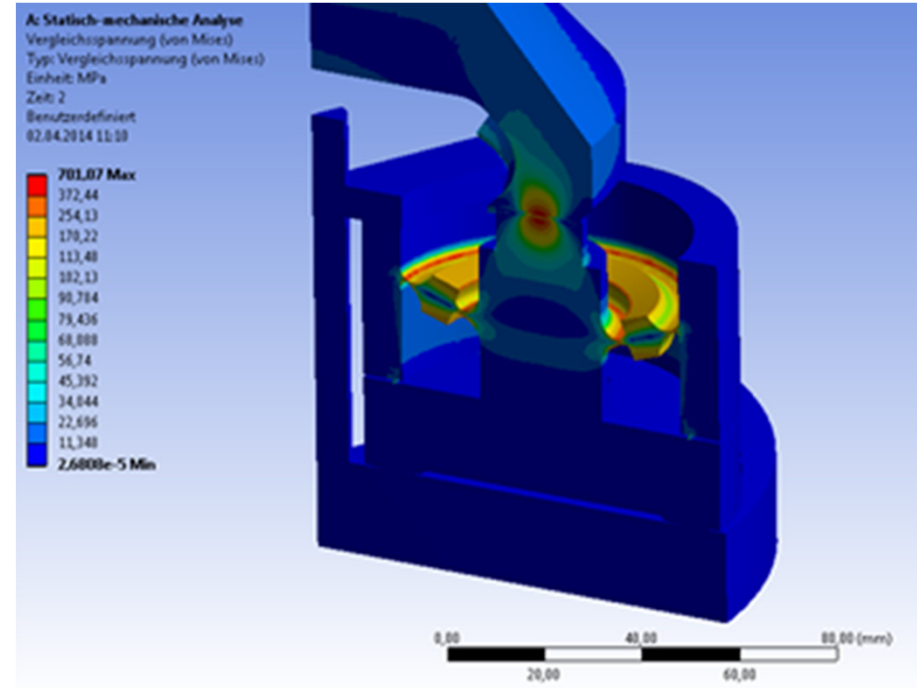
without a lead

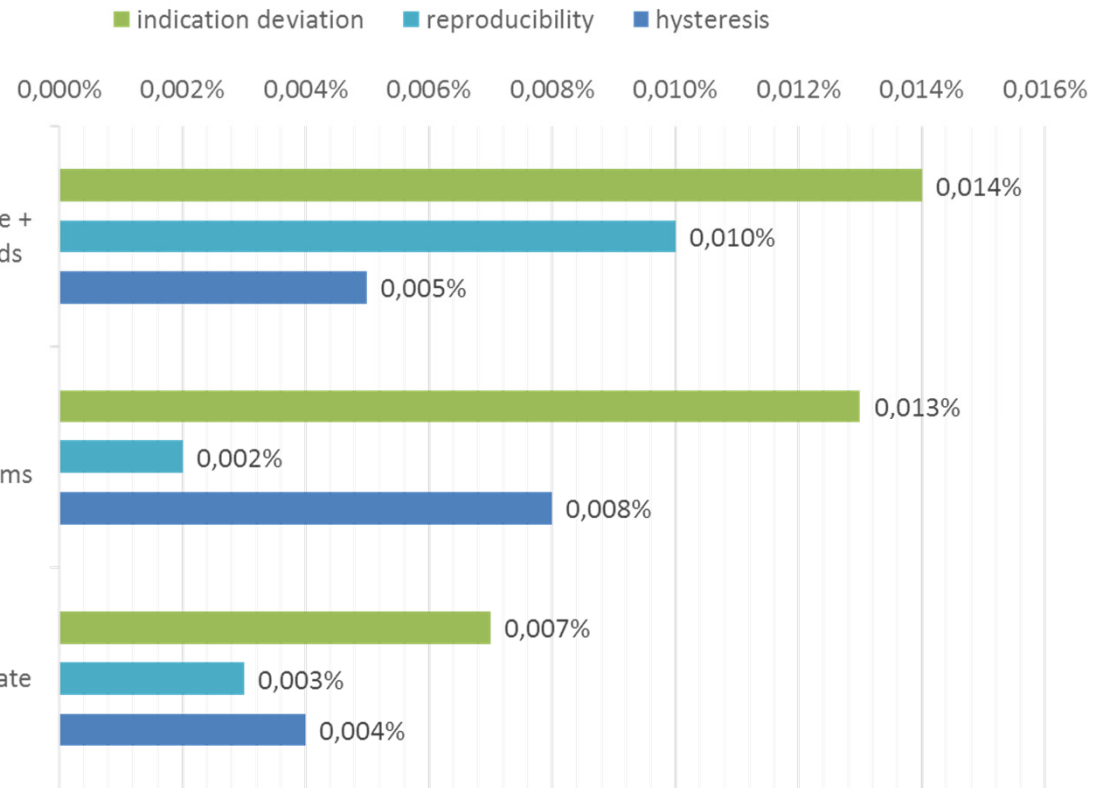
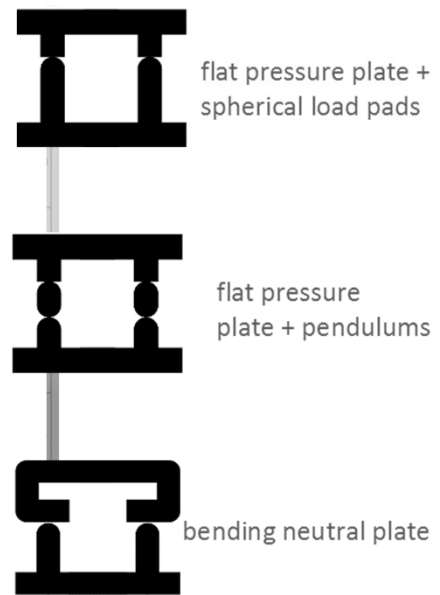
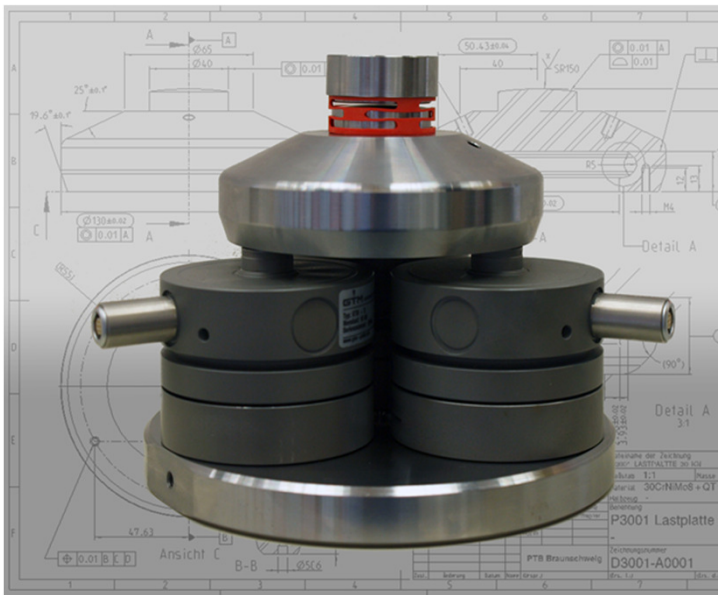


numerical simulation of deformation behavior



cross force generation: $0.01\% \cdot F_0$





d can not be totally reduced to zero !

A theory for the correction of d and the calculation of uncertainties is necessary

d of 30 MN version at 16,5 MN: 0,140 %



0,015 %





Force traceability within the meganewton range

- Home
- The Project
- The Consortium
- Work Packages**
- WP1.3 Built-up Systems**
- WP1.6 Extrapolation
- WP4 Questionnaire
- WP4.1 Application conditions
- WP4.2 Parameters and coefficients
- WP4.3 Uncertainty contributions
- WP4.4 Software tool
- Publications
- News & Events
- Register
- Members Area
- Contact

WP1 Force transfer standards in the highest range up to 50 MN

WP1 has six tasks. Here we publish the results of these tasks.

Task 1.3 - Built-up Systems

An [Excel file](#) for offline use can be downloaded.

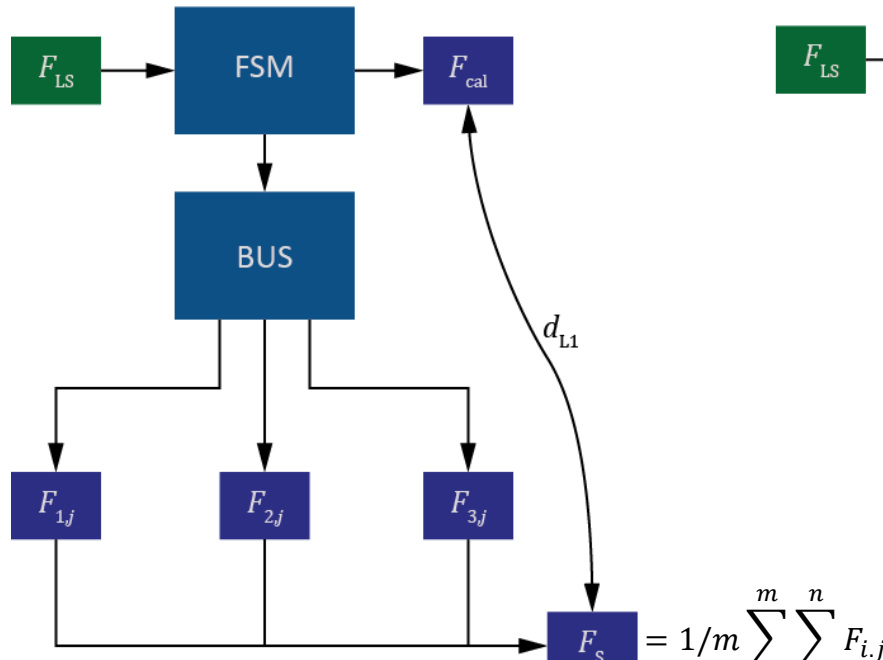
<https://www.ptb.de/emrp/3294.html>

Questions?

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The research leading to these results has received funding from the European Union on the basis of Decision No 912/2009/EC.
Last updated: 2017-05-24

calibration of a BU system



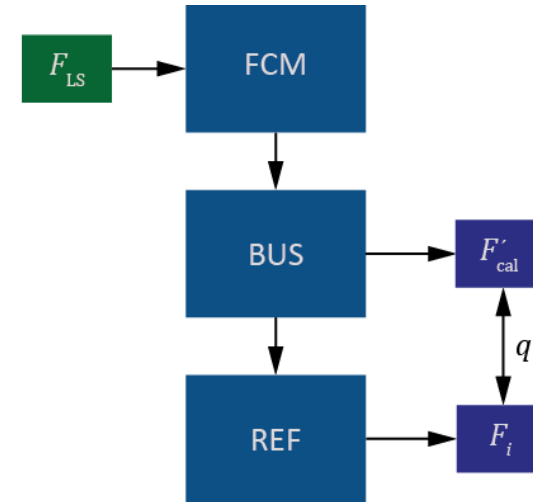
with: m : the number of measurement series and
 n : the number of transducers

$$F_s = 1/m \sum_{j=1}^m \sum_{i=1}^n F_{i,j}$$

$$d_L = \frac{1}{m} \sum_{j=1}^m d_{L,j} = \frac{1}{m} \sum_{j=1}^m \frac{F_{S,j} - F_{LS}}{F_{LS}}$$

$$u^2(d_L) = \left(\frac{1}{m \cdot F_{LS}^2} \cdot \sum_{j=1}^m \sum_{i=1}^n F_{i,j} \right)^2 \cdot u^2(F_{LS}) + \left(\frac{1}{m \cdot F_{LS}} \right)^2 \cdot \sum_{j=1}^m \sum_{i=1}^n u^2(F_{i,j}) + u_{\text{stability}}$$

application of a BU system



$$F'_{\text{cal}} = \frac{1}{m(1 + d'_L)} \sum_{j=1}^m F'_{S,j} = \frac{F'_S}{(1 + d'_L)}$$

$$u_c^2(F'_{\text{cal}}) = \left(\frac{u(F'_S)}{1 + d'_L} \right)^2 + \left(\frac{F'_S \cdot u(d'_L)}{(1 + d'_L)^2} \right)^2$$

A



Calibration of BUS in FSM

B



Plausibility Measurement in FCM

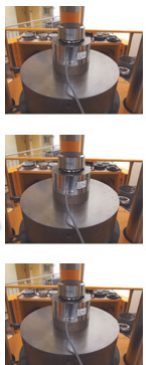
C



Calibration of FCM in full range

Procedure how to calibrate a Force Calibration Facility using a BU-System within 6 steps

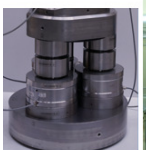
A



Calibration of BUS in FSM

- Calibration (ISO 376) of all single transducers up to nominal load
- Calibration of all single transducers in partial range *if necessary*
- Calibration of whole BUS in nominal range in FSM to determine d

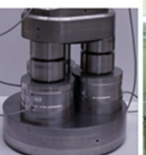
B



Plausibility Measurement in FCM

- Calibration of all single transducers (*can also be used for the calibration in lower range without BUS*)
- Calibration of whole BU-System in partial range of FCM
-> Argument for verification: E_N value of the comparison of d

C



Calibration of FCM in full range with extrapolated d'

- Calibration of whole BU-System in full range if FCM

Plausibility of the deviation d
up to nominal load in the FSM

Indication deviation q of the FCM with
uncertainty



Result

Procedure how to calibrate a Force Calibration Facility using a BU-System

A



Calibration of BUS in FSM

- Calibration of all single transducers
- (Calibration of all single transducers in partial range if necessary)
- Calibration of whole BUS in nominal range if FCM to determine d

Why?

If nominal load of the single transducer calibration differs too much (50%) from the highest load within the BUS calibration at the FSM, than it is important to calibrate the single transducers two times:

Up to nominal load for the estimation of the sensitivity and the uncertainties for the calibration of the FCM.

A second calibration up to maximum load of the single transducer during the BUS calibration at FSM should be preferred for the determination of d .

Example: 50 MN BUS of PTB calibrated in 16,5 MN FSM:



2700,00	2700,00	0,544317	0,542921	2700,00	0,542066	1,395556	7000,00	1,400059	1,397702	7000,00	
3000,00	3000,00	0,604517	0,603121	3000,00	0,601923	1,593945	8000,00	1,598749	1,596392	8000,00	
3300,00	3300,00	0,664716	0,663320	3300,00	0,661773	1,792056	9000,00	1,797174	1,794817	9000,00	
0,00	0,00	0,001457	0,000061	0,00	0,002299	1,989970	10000,00	1,995334	1,992977	10000,00	
						0,000223	0,00	0,002568	0,000211	0,00	
0,00	0,00	0,001424	0,000000	0,00	0,002276	sensitivity and uncertainties					
A1-General information		A1-Measurement data		A1-Uncertainties		A2-Measurement data		A2-Uncertainties		B1-General information	

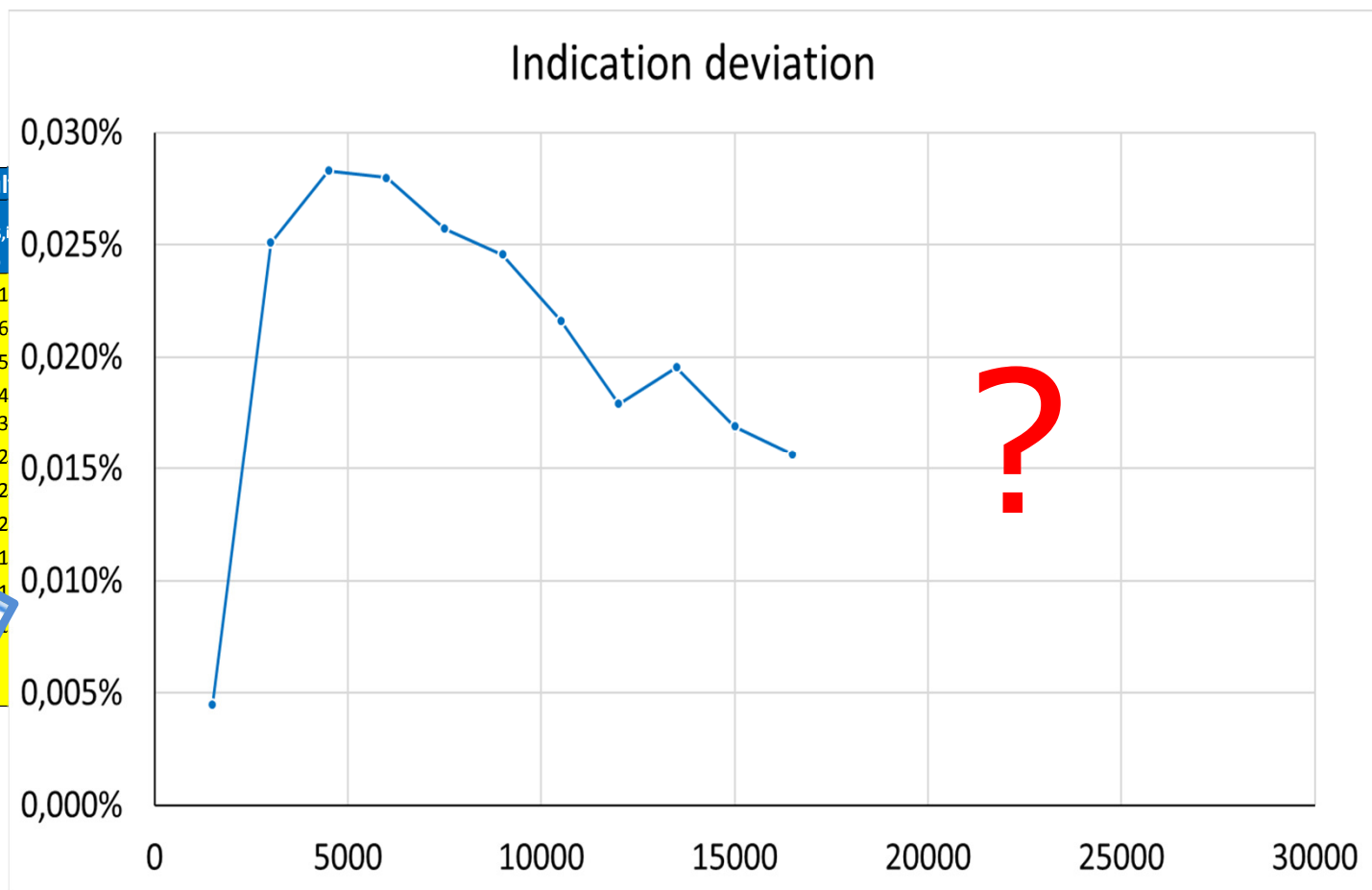
d_L and uncertainties

sensitivity and uncertainties

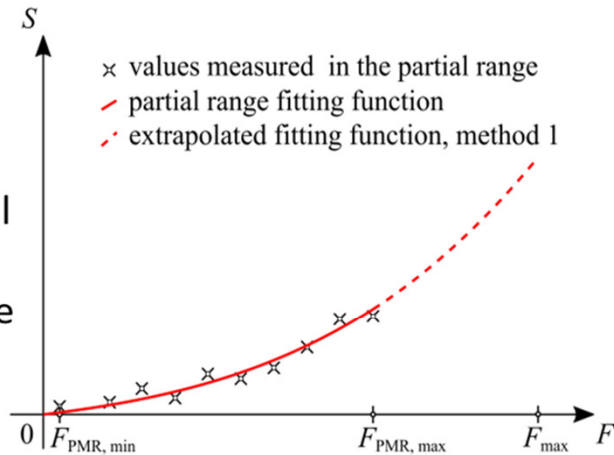
Extrapolation of d_L

Load Step		Indication deviation		Calibration result	
F_{LS} kN	$W(F_{LS})$ %	d_L %	$U(d_L)$ %	$F_{S,int}$ kN	$W(F_{S,int})$ %
1500	0,010%	0,005%	0,022%	1500,43	0,031
3000	0,010%	0,025%	0,022%	3000,84	0,026
4500	0,010%	0,028%	0,022%	4501,21	0,025
6000	0,010%	0,021%	0,021%	6001,55	0,024
7500	0,010%	0,021%	0,021%	7501,84	0,023
9000	0,010%	0,021%	0,021%	9002,09	0,022
10500	0,010%	0,021%	0,021%	10502,29	0,022
12000	0,010%	0,018%	0,021%	12002,44	0,022
13500	0,010%	0,020%	0,021%	13502,59	0,021
15000	0,010%	0,017%	0,021%	15002,74	0,021
16500	0,010%	0,016%	0,021%	16502,89	0,021

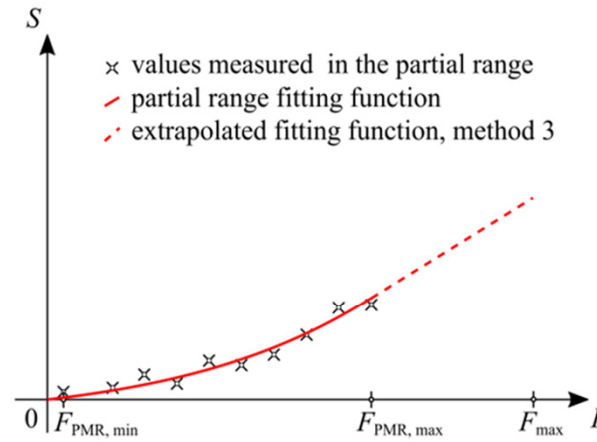
<https://www.ptb.de/emrp/3294.html>



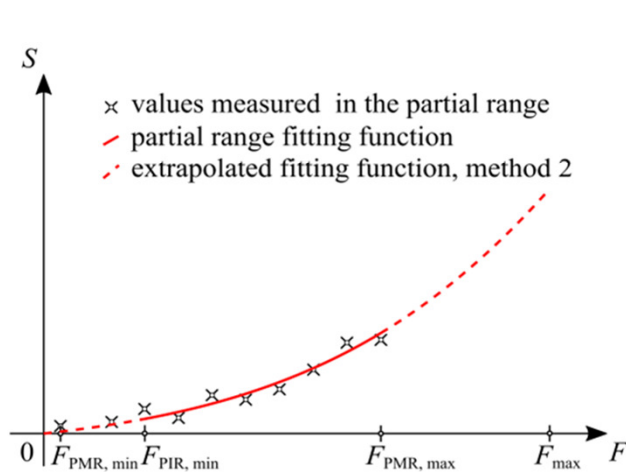
Method 1:
The fitting function found for the partial range is used in the full measuring range



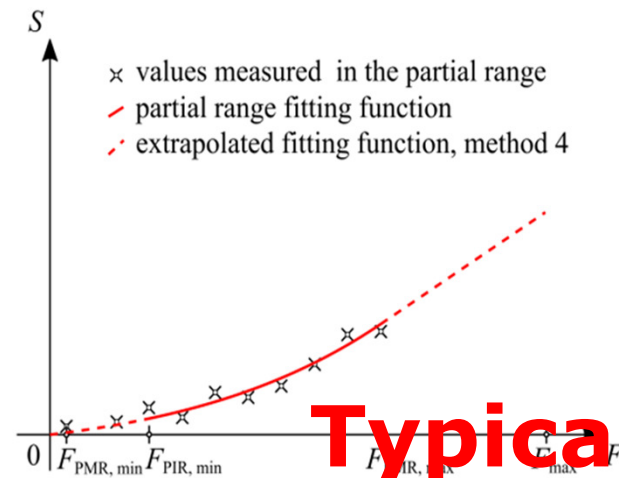
Method 3:
Uses the fitting function found in method 1 with the difference that its extension to larger forces follows the tangent to the function in the end point of the partial range



Method 2:
Many transducers show a nonlinear behaviour at lowest forces. This range is not used for the calculation of the partial range fitting function.



Method 4:
Uses the fitting function found in method 2 with a nonlinear behaviour at lowest forces and the tangent at the endpoint as method 3



Typical for BUS

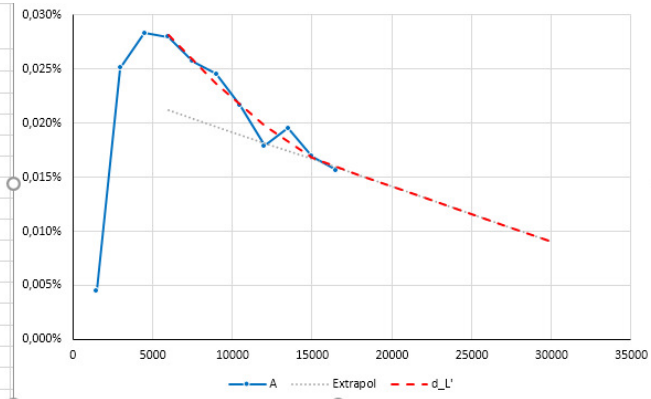
„Engine for type of extrapolation“

- Developed for the extrapolation of force transducer signals in case of a partial calibration (EMRP, Task 1.6). This works also for d_L .
- Compares two partial calibrations to find the best strategy to extrapolate from smaller to bigger partial calibration.
- Deviation is shown in colors according to ISO 376 classes. (green 00, yellow 05, orange 1, red 2, blue none)

Detailed information in the final report of the EMRP project on its homepage

SUMMARY						linear						quadratic						cubic											
EXTRAPOLATION1						EXTRAPOLATION2						EXTRAPOLATION3						EXTRAPOLATION4											
Force in kN	Mean	75%	50%	25%	0%	Force in kN	Mean	75%	50%	25%	0%	Force in kN	Mean	75%	50%	25%	0%	Force in kN	Mean	75%	50%	25%	0%						
100	-0.041493	-0.598%	-0.347%	-0.251%	0%	100	-0.041493	-0.598%	-0.347%	-0.251%	0%	100	-0.041493	-0.598%	-0.347%	-0.251%	0%	100	-0.041493	-0.598%	-0.347%	-0.251%	0%	100	-0.041493	-0.598%	-0.347%	-0.251%	0%
250	-0.103642	-0.440%	-0.279%	-0.184%	0%	250	-0.103642	-0.440%	-0.279%	-0.184%	0%	250	-0.103642	-0.440%	-0.279%	-0.184%	0%	250	-0.103642	-0.440%	-0.279%	-0.184%	0%	250	-0.103642	-0.440%	-0.279%	-0.184%	0%
500	-0.207283	-0.420%	-0.260%	-0.164%	0%	500	-0.207283	-0.420%	-0.260%	-0.164%	0%	500	-0.207283	-0.420%	-0.260%	-0.164%	0%	500	-0.207283	-0.420%	-0.260%	-0.164%	0%	500	-0.207283	-0.420%	-0.260%	-0.164%	0%
1000	-0.414559	-0.371%	-0.210%	-0.114%	0%	1000	-0.414559	-0.371%	-0.210%	-0.114%	0%	1000	-0.414559	-0.371%	-0.210%	-0.114%	0%	1000	-0.414559	-0.371%	-0.210%	-0.114%	0%	1000	-0.414559	-0.371%	-0.210%	-0.114%	0%
1500	-0.621045	-0.291%	-0.131%	-0.035%	0%	1500	-0.621045	-0.291%	-0.131%	-0.035%	0%	1500	-0.621045	-0.291%	-0.131%	-0.035%	0%	1500	-0.621045	-0.291%	-0.131%	-0.035%	0%	1500	-0.621045	-0.291%	-0.131%	-0.035%	0%
2000	-0.827309	-0.201%	-0.040%	0.056%	0%	2000	-0.827309	-0.201%	-0.040%	0.056%	0%	2000	-0.827309	-0.201%	-0.040%	0.056%	0%	2000	-0.827309	-0.201%	-0.040%	0.056%	0%	2000	-0.827309	-0.201%	-0.040%	0.056%	0%
2500	-1.033224	-0.114%	0.043%	0.146%	0%	2500	-1.033224	-0.114%	0.043%	0.146%	0%	2500	-1.033224	-0.114%	0.043%	0.146%	0%	2500	-1.033224	-0.114%	0.043%	0.146%	0%	2500	-1.033224	-0.114%	0.043%	0.146%	0%
3000	-1.238790	-0.024%	0.121%	0.232%	0%	3000	-1.238790	-0.024%	0.121%	0.232%	0%	3000	-1.238790	-0.024%	0.121%	0.232%	0%	3000	-1.238790	-0.024%	0.121%	0.232%	0%	3000	-1.238790	-0.024%	0.121%	0.232%	0%
3500	-1.444059	0.057%	0.218%	0.318%	0%	3500	-1.444059	0.057%	0.218%	0.318%	0%	3500	-1.444059	0.057%	0.218%	0.318%	0%	3500	-1.444059	0.057%	0.218%	0.318%	0%	3500	-1.444059	0.057%	0.218%	0.318%	0%
4000	-1.649776	0.141%	0.302%	0.399%	0%	4000	-1.649776	0.141%	0.302%	0.399%	0%	4000	-1.649776	0.141%	0.302%	0.399%	0%	4000	-1.649776	0.141%	0.302%	0.399%	0%	4000	-1.649776	0.141%	0.302%	0.399%	0%
4500	-1.853609	0.220%	0.382%	0.479%	0%	4500	-1.853609	0.220%	0.382%	0.479%	0%	4500	-1.853609	0.220%	0.382%	0.479%	0%	4500	-1.853609	0.220%	0.382%	0.479%	0%	4500	-1.853609	0.220%	0.382%	0.479%	0%
5000	-2.057923	0.300%	0.462%	0.559%	0%	5000	-2.057923	0.300%	0.462%	0.559%	0%	5000	-2.057923	0.300%	0.462%	0.559%	0%	5000	-2.057923	0.300%	0.462%	0.559%	0%	5000	-2.057923	0.300%	0.462%	0.559%	0%
0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%

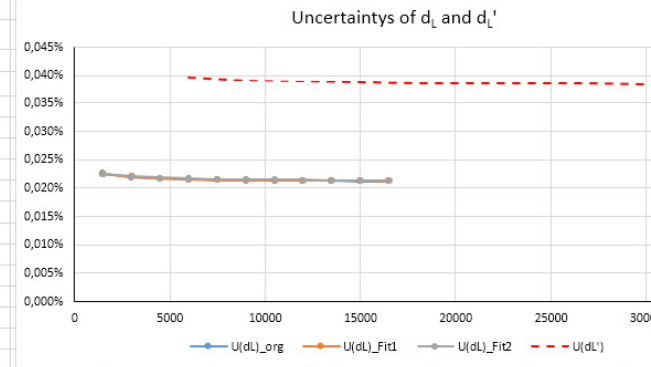
Load Step		Indication deviation			Load Step		Indication deviation		
FLS	kN	dL	U(dL)	dL (FitA)	FLS	kN	dL	U(dL)	dL (FitB)
		%	%	%			%	%	%
1500,00		0,005%	0,022%	0,035%	3000		0,103%	0,103%	0,106%
3000,00		0,025%	0,022%	0,033%	4500		0,116%	0,103%	0,112%
4500,00		0,028%	0,022%	0,030%	6000		0,112%	0,102%	0,109%
6000,00		0,028%	0,021%	0,028%	7500		0,097%	0,102%	0,100%
7500,00		0,026%	0,021%	0,026%	9000		0,084%	0,102%	0,086%
9000,00		0,025%	0,021%	0,024%	10500		0,068%	0,102%	0,070%
10500,00		0,022%	0,021%	0,022%	12000		0,054%	0,102%	0,053%
12000,00		0,018%	0,021%	0,020%	13500		0,040%	0,102%	0,038%
13500,00		0,020%	0,021%	0,018%	15000		0,028%	0,102%	0,025%
15000,00		0,017%	0,021%	0,017%	16500		0,016%	0,102%	0,018%
16500,00		0,021%	0,021%	0,016%					



<https://www.ptb.de/emrp/3294.html>

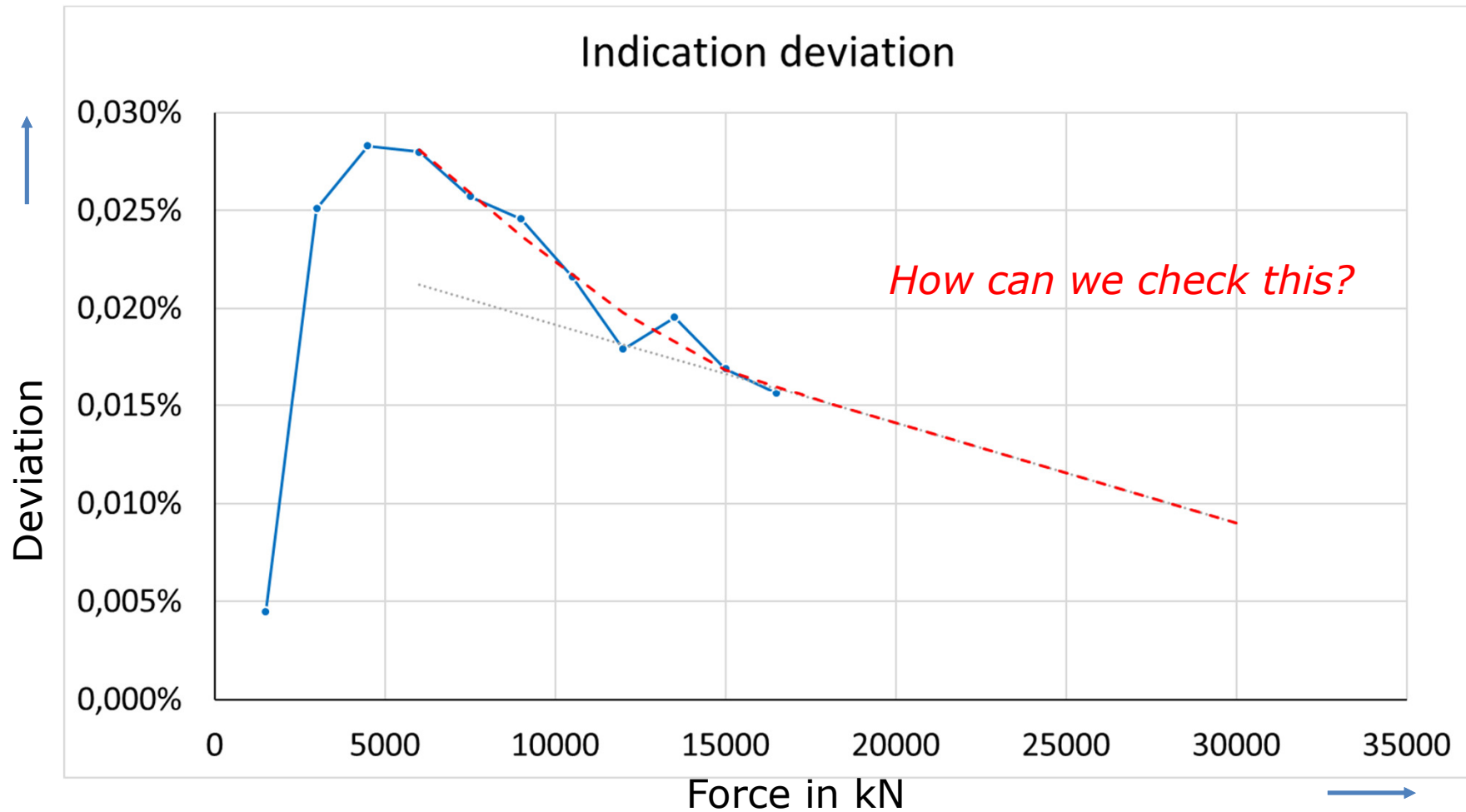
Load Step		Indication deviation			Load Step		Indication deviation		
FLS	kN	U_{org}	U_{Fit1}	U_{Fit2}	FLS	kN	dL'	U(dL')	
		%	%	%			%	%	
1500,00		0,022%	0,022%	0,022%	6000		0,028%	0,040%	
3000,00		0,022%	0,022%	1,20E-07	7500		0,024%	0,039%	
4500,00		0,022%	0,022%	4,36E-07	9000		0,020%	0,039%	
6000,00		0,021%	0,021%	-2,63E-07	10500		0,017%	0,039%	
7500,00		0,021%	0,021%	-5,45E-07	12000		0,015%	0,039%	
9000,00		0,021%	0,021%	-4,53E-07	13500		0,014%	0,039%	
10500,00		0,021%	0,021%	-1,28E-07	15000		0,012%	0,038%	
12000,00		0,021%	0,021%	2,46E-07	16500		0,011%	0,038%	
13500,00		0,021%	0,021%	4,54E-07	30000		0,009%	0,038%	
15000,00		0,021%	0,021%	3,07E-07					
16500,00		0,021%	0,021%	-4,19E-07					

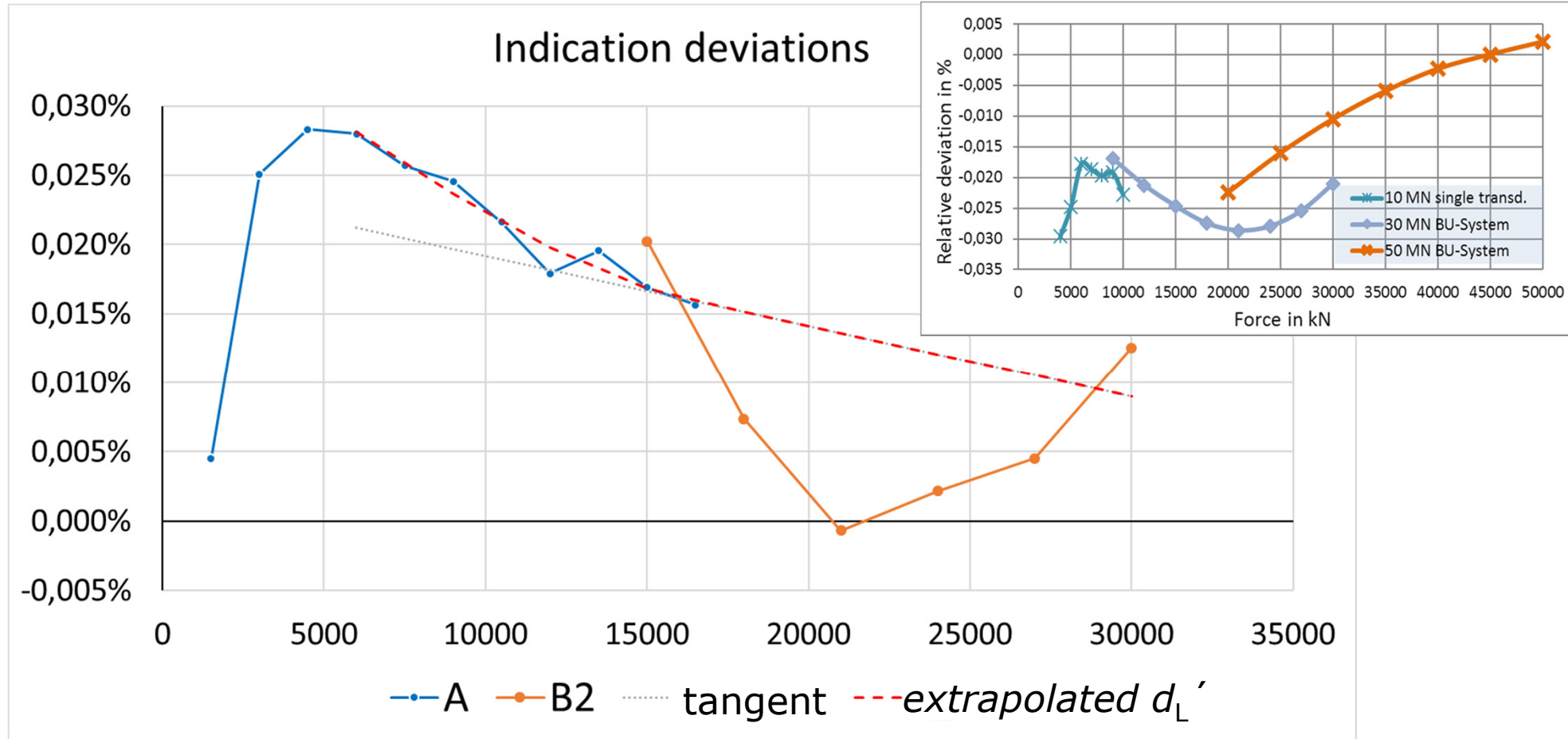
Results of the extrapolation:



Fits:

	$d_L(F) = a_1 \cdot F + a_2 \cdot F^2 + a_3 \cdot F^3 + a_4$				Tangente	Korrektur:
	a_1	a_2	a_3	a_4		
A:	-1,255E-08	-4,658E-13	2,797E-17	3,671E-04	-5,08E-09	0,00E+00
B:	2,319E-07	-3,138E-11	9,517E-16	6,248E-04	2,43E-04	0,00E+00
1:	-4,369E-09	3,786E-13	-1,100E-17	2,297E-04		
2:	-4,369E-09	3,786E-13	-1,100E-17	2,309E-04	m:	1,8



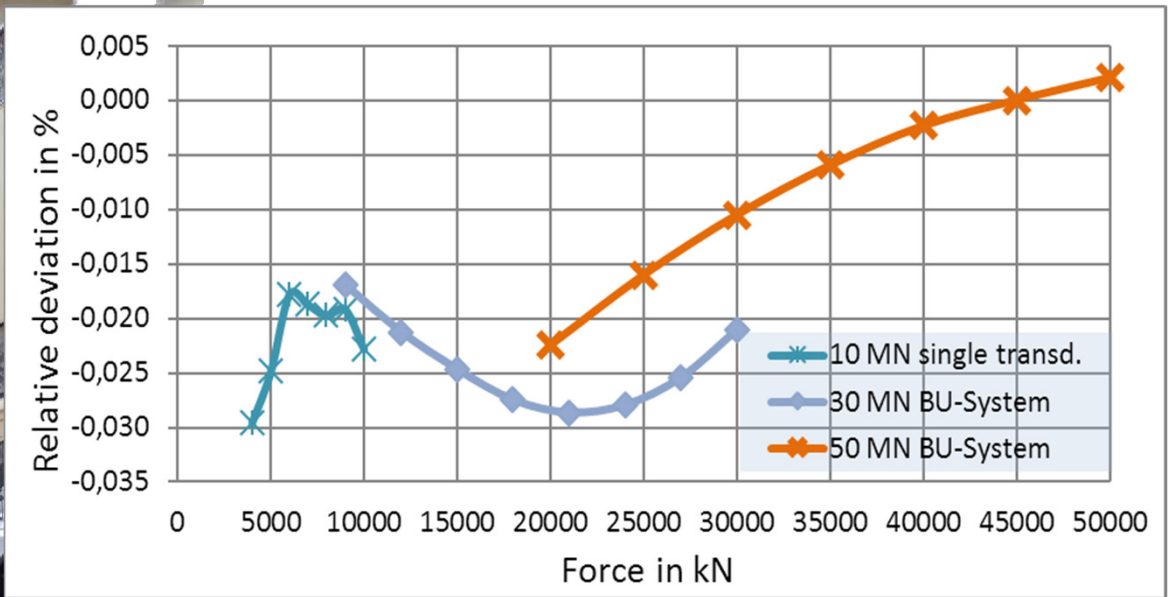


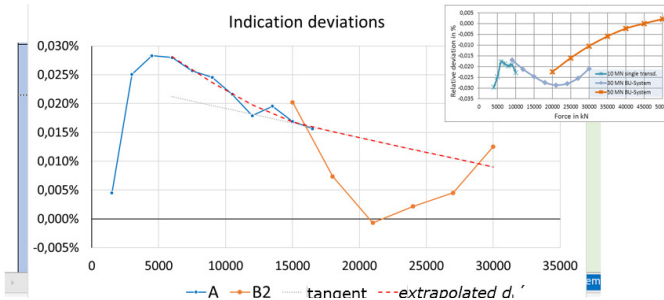
uncertainty contributions			
rotation	repeatability	creep	drift of the zero signal
w_2	w_3	w_5	w_6
0,002%	0,002%	0,004%	0,006%
0,002%	0,001%	0,004%	0,006%
0,002%	0,000%	0,004%	0,006%
0,002%	0,000%	0,004%	0,006%
0,001%	0,000%	0,004%	0,006%
0,001%	0,001%	0,004%	0,006%
0,001%	0,001%	0,004%	0,006%
0,001%	0,000%	0,004%	0,006%
0,001%	0,000%	0,004%	0,006%
0,000%	0,000%	0,004%	0,006%
0,000%	0,001%	0,004%	0,006%



Load Step		Indication deviation		Calibration result	
F_{LS} kN	$W(F_{LS})$ %	d %	$U(d_L)$ %	$F_{S.int}$ kN	$W(F_{S.int})$ %
1500	0.010%	0.005%	0.022%	1500.43	0.031%
3000	0.010%	0.025%	0.022%	3000.84	0.026%
4500	0.010%	0.028%	0.022%	4501.21	0.025%
6000	0.010%	0.028%	0.021%	6001.55	0.024%
7500	0.010%	0.026%	0.021%	7501.84	0.023%
9000	0.010%	0.025%	0.021%	9002.09	0.022%
10500	0.010%	0.022%	0.021%	10502.29	0.022%
12000	0.010%	0.018%	0.021%	12002.44	0.022%
13500	0.010%	0.020%	0.021%	13502.53	0.021%
15000	0.010%	0.017%	0.021%	15002.57	0.021%
16500	0.010%	0.016%	0.021%	16502.53	0.021%

- 5 single transducer class 00 according to ISO 376 (even VN class as a better class in GTM's notification)
- Highly effective compensation of bending moments and cross forces. reproducibility is much lower than 0.01%
- Ultracompact. stiff structure
- The low sensitivity against cross forces and the effective reduction of the generation of such components by the stiffness result in a very low indication deviation d of the system





<https://www.ptb.de/emrp/3294.html>

$$F'_{cal} = \frac{1}{m(1 + d'_L)} \sum_{j=1}^m F'_{S,j} = \frac{F'_S}{(1 + d'_L)}$$

BUS evaluation template of EMRP SIB 63

Verification B2 measurement



„Extrapolation Engine“ for *d*

A **Calibration of BUS in FSM**

- Calibration of all single transducers
- (Calibration of all single transducers in partial range if necessary)
- Calibration of whole BUS in nominal range if FCM to determine *d*

Why?

If nominal load of the single transducer calibration differs too much (50%) from the nominal load of it within the BUS calibration at the FSM, than it is important to calibrate the single transducers two times:

Up to nominal load for the estimation of the sensitivity and the uncertainties for the calibration of the FCM.

A second calibration up to maximum load of the single transducer during the BUS calibration at FSM should be preferred for the determination of *d*.

Example: 50 MN BUS of PTB calibrated in 16,5 MN FSM:

<i>d</i> , and uncertainties				sensitivity and uncertainties			
2700,00	2700,00	0,548117	0,542921	2700,00	0,542066	1,385556	7000,00
3000,00	3000,00	0,604517	0,603121	3000,00	0,603323	1,593345	8000,00
3300,00	3300,00	0,664716	0,663320	3300,00	0,663773	1,780556	9000,00
0,00	0,00	0,001424	0,000964	0,00	0,002289	0,000223	0,00
0,00	0,00	0,001424	0,000000	0,00	0,002276	0,000258	0,000211

Partial A2 calibration if necessary

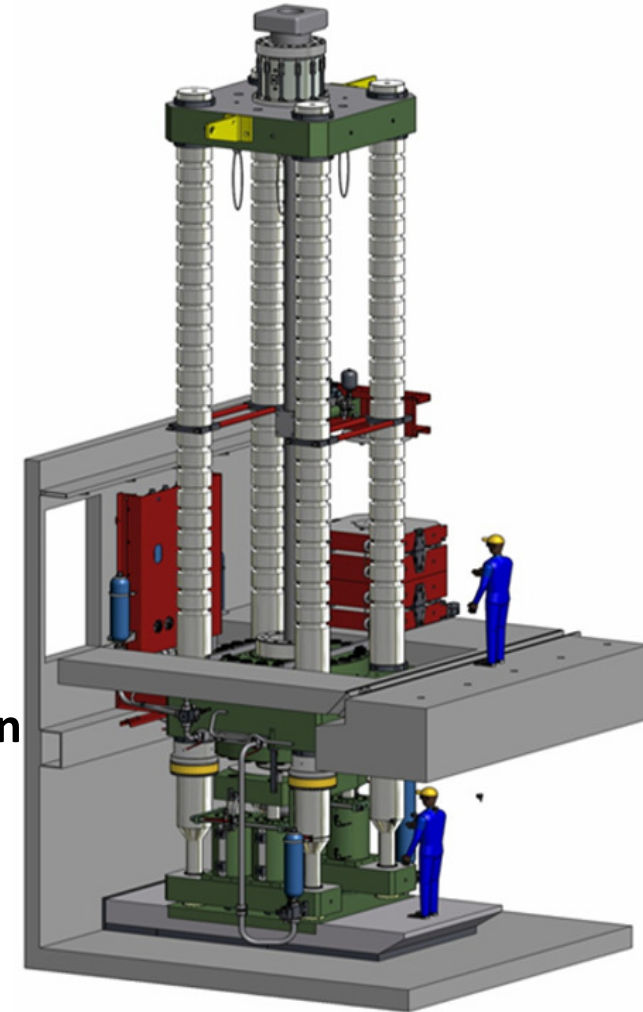
ISO 7500-1



“Qualified” BUS



- **Static / dynamic force in tension and compression**
 - max. stat. / dyn. Force: 33 MN / 24 MN
 - max. piston stroke : 0.4 m
 - max. frequency: 5 Hz (at 5 mm stroke)
- **Dimension of test specimen in tension**
 - max. length: 10.3 m
 - max. diameter at the anchor coupler : 0.5 m
- **Dimension of test specimen in compression**
 - max. height: 5.0 m
 - max. diameter: 1.1 m / 1.1 m

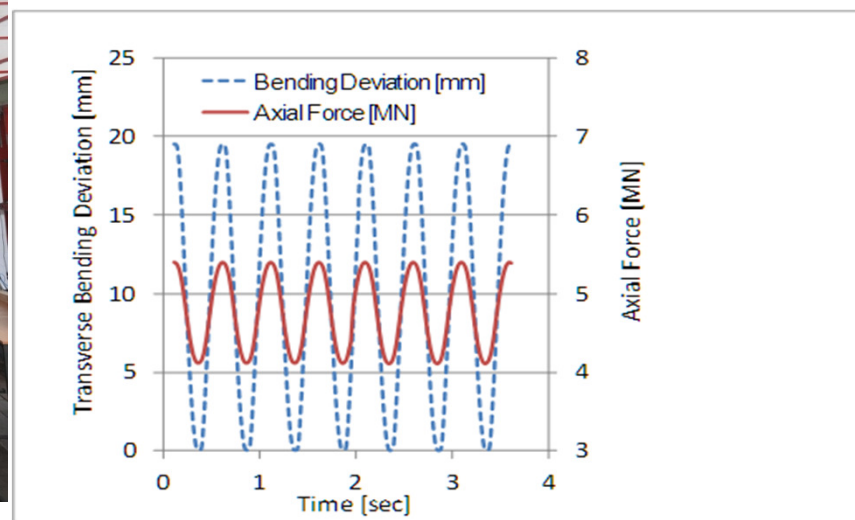




Dynamic test of a bridge stay cable

Forth Replacement Crossing
Queensferry Bridge,
Edinburgh/Scotland

- Axial dynamic load
- Synchronized bending moment loaded to the stay cable to investigate influence of wind/rain induced sideways swinging



3. Prüfmittel/Test equipment

3.1 Kraftaufnehmer/Force transducer

30 MN Build-Up System mit elektrischer Verformungsmessung (PTB)
 30 MN Build-Up system with electrical deformation measurement (PTB)

Hersteller: GTM Testing and Metrology GmbH
 Manufacturer: 64404 Bickenbach

Typ: 3 x 10 MN LF
 Type:

Seriennummern: 64042; 64053; 64111
 Serial numbers:

3.2 Anzeigegerät/Display device

Digitales Anzeigegerät: Typ: DMP 41, Nr.: 819192502 PTB
 Digital indicator:

Hersteller: Hottinger Baldwin Messtechnik GmbH
 Manufacturer: 64293 Darmstadt

Messkanäle: 1-3
 Measuring channels:

Kalibrierwert: 2,500001
 Calibration signal:

Auflösung in mV/V: 0,000001
 Resolution in mV/V:

Speisespannung: 5 V
 Excitation voltage:

Tiefpassfilter: 0,10 Hz Be
 Low-pass filter:

Messbereich:
 Measuring range:



$$q = \Delta F(F'_S) = F_i(F'_S) - F'_{cal}(F'_S)$$

Tabelle 7: Mean values of the force indication of the standard, absolute and relative resolution of the test machine, mean value of the indication deviation, repeatability


Kraft in kN Force in kN	Mittelwert in kN mean value in kN	Auflösung der Anzeige der Prüfmaschine in kN Indicated resolution of the testing machine in kN	Relative Auflösung in % Relative indication resolution in %	Mittlere Anzeige- abweichung in % Indication deviation in %	Wiederhol- präzision in % Repeatability in %
F	\bar{F}	r	a	q	b
3000	2987,61	0,1	0,003	0,415	0,164
6000	5973,53	0,1	0,002	0,443	0,065
9000	8994,81	0,1	0,001	0,058	0,038
12000	12007,85	0,1	0,001	-0,065	0,032
15000	14999,84	0,1	0,001	0,001	0,024
18000	17981,42	0,1	0,001	0,103	0,031
21000	20972,01	0,1	0,000	0,133	0,015
24000	23983,24	0,1	0,000	0,070	0,023
27000	27002,49	0,1	0,000	-0,009	0,020
30000	29979,42	0,1	0,000	0,069	0,028

3.3 Gültigkeit der Kalibrierung/Validity of the calibration

Kalibrierzeichen: 12209 PTB 16; 12212 PTB 16; 12213 PTB 16
 Calibration mark:

Gültigkeit bis: 24.11.2018
 Valid until:



 **Physikalisch-Technische Bundesanstalt
Braunschweig und Berlin**
Nationales Metrologieinstitut



Kalibrierschein Calibration Certificate

Gegenstand:
Object:

Zug-Druckprüfmaschine 30 MN
Tension/compression testing machine

Hersteller:
Manufacturer:

Typ:
Type:

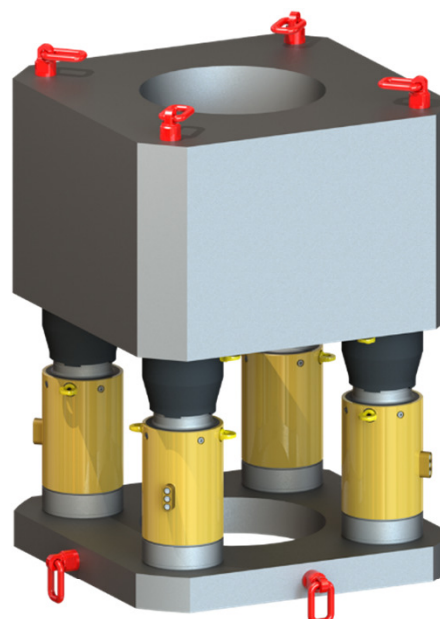
Kennnummer:
Serial No.:

Auftraggeber:
Applicant:





Calibration of the Transfer-Standard in PTB's 16,5 MN FSM



Dissemination of the quantity Force to the new 30 MN Reference System



Thank you very much for your attention !



**Physikalisch-Technische Bundesanstalt
Braunschweig und Berlin**

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38116 Braunschweig / GERMANY

Dr. Falk Tegtmeier
Working group 1.23 „Force Measuring Technique“

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